

$$1) \quad V_C = \omega_{CD} R_2 \quad \omega_A = \frac{V_C}{R_1} \quad V_R = \omega_A \times 2R_1$$

$$\omega_R = \frac{V_R}{R_1 + R_2}$$

$$2) \quad \text{از مرکز آبی بدون} \Rightarrow \omega_{AB} = 0$$

$$\begin{pmatrix} a_B \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} a_{AB} \\ v_B^2/r_{AC} \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ \alpha_{AB} \end{pmatrix} \times \begin{pmatrix} d \\ r_{AC} \\ 0 \end{pmatrix} \rightarrow \begin{matrix} a_A = \begin{pmatrix} -7 \\ 12 \end{pmatrix} \frac{ft}{s^2} \\ \alpha_{AB} = -3 \frac{rad}{s^2} \end{matrix}$$

3)

$$M = M_1 + M_2, \quad I_O = \frac{1}{12} M_1 (b^2 + c^2) + M_1 (a + \frac{c}{2})^2 + \frac{1}{3} M_2 a^2$$

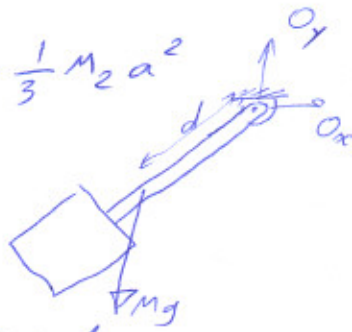
$$d = \frac{M_1 (a + \frac{c}{2}) + M_2 (\frac{a}{2})}{M}$$

$$O_x = Md \alpha \sin \theta + Md \omega^2 \cos \theta$$

$$mg d \cos \theta = I_O \alpha$$

$$O_y - Mg = -Md \alpha \cos \theta + Md \omega^2 \sin \theta$$

$$\Rightarrow \begin{matrix} \alpha = 15.65 \frac{rad}{sec^2} \\ O_x = 54.8 N \\ O_y = 41.2 N \end{matrix}$$



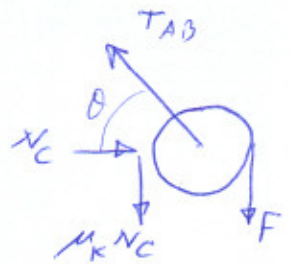
$$4) \quad \theta = \tan^{-1} \frac{a}{b}$$

$$N_C - T_{AB} \cos \theta = 0$$

$$T_{AB} \sin \theta - \mu_k N_C - Mg - F = 0$$

$$F \cdot b - \mu_k N_C b = M k_A^2 \alpha$$

$$\Rightarrow \begin{matrix} N_C = 102.818 N \\ T_{AB} = 267.327 N \\ \alpha = 7.281 \frac{rad}{s^2} \end{matrix}$$



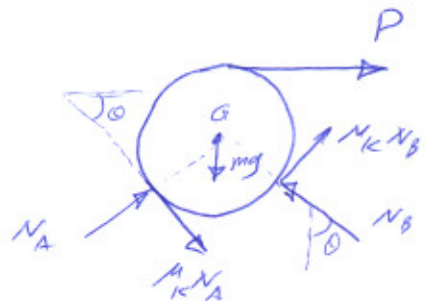
$$5) \quad P - (N_B - N_A) \sin \theta + \mu_k (N_A + N_B) \cos \theta = 0$$

$$(N_A + N_B) \cos \theta + \mu_k (N_B - N_A) \sin \theta - mg = 0$$

$$[\mu_k (N_A + N_B) - P] r = \frac{1}{2} m r^2 \alpha$$

$$\Rightarrow N_A + N_B = \frac{mg - \mu_k P}{(1 + \mu_k^2) \cos \theta}, \quad N_B - N_A = \frac{\mu_k mg + P}{(1 + \mu_k^2) \sin \theta}$$

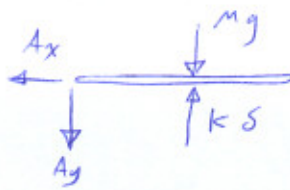
$$\alpha = -\frac{2 \mu_k}{mr} \cdot \frac{mg - \mu_k P}{(1 + \mu_k^2) \cos \theta} + \frac{2P}{mr}$$



$$6) -Mga + k\delta a = \frac{1}{3} M (a+b)^2 \alpha$$

$$A_x = 0$$

$$-A_y - Mg + k\delta = M\alpha \frac{a+b}{2} \Rightarrow \alpha = 23.1 \frac{\text{rad}}{\text{s}^2}, A_x = 0, A_y = 289 \text{ N}$$



7)

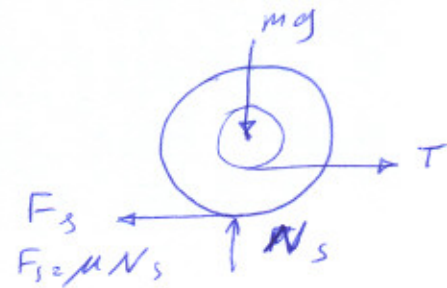
$$T - F_s = ma_m$$

$$N_s - mg = 0 \rightarrow N_s = mg$$

$$T r_i - F_s r_o = -m k^2 \alpha$$

$$F_{s, \text{max}} = \mu N_s, a_m = r_i \alpha, a_c = (r_o - r_i) \alpha$$

$$\Rightarrow T = 2.32 \text{ kN}, \alpha = 1.25 \frac{\text{rad}}{\text{sec}^2}, a_c = 1.348 \frac{\text{m}}{\text{s}^2}$$



$$8) \phi = \sin^{-1} \frac{r}{L}$$

$$N_c L \cos \phi - m_d g L \cos(\theta - \phi) - m_b g \frac{L}{2} \cos(\theta - \phi) = \frac{1}{2} m_d r^2 \alpha - m_d a_A r - m_b a_A \frac{r}{2}$$

$$-F_c + (m_d + m_b) g \sin \theta = (m_b + m_d) a_A$$

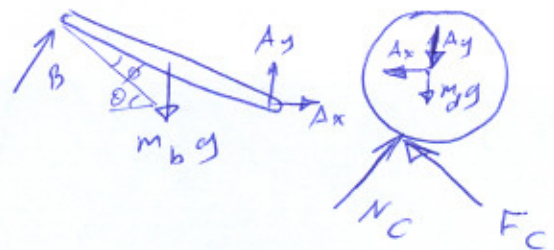
$$F_c r = \frac{1}{2} m_d r^2 \alpha$$

$$a_A = r \alpha, F_{\text{max}} = \mu_s N_c$$

$$\rightarrow F_c > F_{\text{max}}$$

$$\rightarrow F_c = \mu_k N_c$$

$$\Rightarrow \begin{cases} N_c = 67.966 \text{ N} \\ F_c = 6.797 \text{ N} \\ F_{\text{max}} = 10.195 \text{ N} \end{cases} \Rightarrow \alpha = 5.664 \frac{\text{rad}}{\text{s}^2}$$



$$\begin{aligned} N_c &= 67.966 \text{ N} \\ F_c &= 6.797 \text{ N} \\ F_{\text{max}} &= 10.195 \text{ N} \\ \alpha &= 5.664 \frac{\text{rad}}{\text{s}^2} \end{aligned}$$

$$g) T_1 + U_1 = T_2 + U_2 \rightarrow 0 + 0 = 0 + \frac{1}{2} k [\sqrt{(a+b)^2 + a^2} - b] - Mg \frac{a}{2}$$

$$\Rightarrow k = 42.8 \frac{\text{N}}{\text{m}}$$

$$10) \quad M g d = \frac{1}{2} M v_G^2 + \frac{1}{2} I_G \omega^2 + M g (d-r)$$

$$v_G = \omega \left(\frac{d}{2} - r \right) \rightarrow \omega = 12.4, \quad v_G = 0.62$$

$$v_A = \omega \hat{k} \times \frac{d}{2} (-\hat{i} + \hat{j}) = -2.48 (\hat{i} + \hat{j}) \text{ m/s} \rightarrow |v_A| = 3.5 \text{ m/s}$$

$$11) \quad 0 + 0 = \frac{1}{2} \frac{m_A r^2}{2} \left(\frac{v_b}{r} \right)^2 + \frac{1}{2} \left(\frac{m_B R^2}{2} \right) \left(\frac{v_b}{R} \right)^2 + \frac{1}{2} m_b v_b^2 - m_b g d$$

$$\rightarrow v_b = 1.519 \text{ m/s}$$

$$12) \int_{\theta_0 + 90 \text{ deg}}^{\theta_0} -k \theta d\theta = \frac{1}{2} \cdot \frac{1}{3} M a^2 \omega^2 \rightarrow \theta_0 = 0 \quad \text{زنی کسره}$$

$$\text{پس: } \frac{k}{2} \times \left(\frac{\pi}{2} \right)^2 = \frac{1}{2} \cdot \frac{1}{3} M a^2 \omega^2$$

$$\Rightarrow \omega = \sqrt{\frac{3 k \pi^2}{4 M a^2}}$$

$$13) \quad m_b g r \sin \theta = (m_b r^2 + m_w k_G^2) \cdot \alpha$$

تاقبل از لغزش :

$$\rightarrow \alpha = \frac{m_b g r}{m_b r^2 + m_w k_G^2} \cdot \sin \theta$$

$$[\Sigma F_n = m a_n] \rightarrow F_N - m_b g \cos \theta = -m_b r \omega^2$$

$$[\Sigma F_t = m a_t] \rightarrow F_N - m_b g \sin \theta = -m_b r \alpha$$

در لحظه لغزش :

$$\Rightarrow \frac{\omega^2}{2} = \frac{m_b g r}{m_b r^2 + m_w k_G^2} (1 - \cos \theta)$$

$$\Rightarrow \alpha = 0.107 \frac{\text{rad}}{\text{s}^2}, \quad \omega = 0.238 \frac{\text{rad}}{\text{s}}, \quad \theta = 29.8 \text{ deg}$$